FCAS MODEL IN NEMDE

SCALING, ENABLEMENT, AND CO-OPTIMISATION OF FCAS OFFERS IN CENTRAL DISPATCH

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IMPORTANT NOTICE

Purpose
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1. INTRODUCTION

AEMO is responsible under the National Electricity Rules (Rules) for ensuring that the power system is operated in a safe, secure and reliable manner, including managing frequency through the procurement of Frequency Control Ancillary Service (FCAS) from suitable generating units and loads.

Under the Rules, the central dispatch process aims to maximise the value of spot market trading by satisfying energy demand and all FCAS requirements at least cost using energy and FCAS offers, subject to technical limits on the provision of those services. AEMO achieves this using the National Electricity Market Dispatch Engine (NEMDE) software.

Sections 2 and 3 of AEMO’s “Guide to Ancillary Services in the National Electricity Market”\(^1\) provide a general description of FCAS, including the nature of FCAS requirements, the structure of FCAS offers and their technical limits, how FCAS offers are used, and the settlement of procured FCAS.

This document describes how the technical limits on FCAS provision are modelled within the NEMDE software, including:

- Limits submitted in FCAS offers.
- Limits telemetered in real-time from automatic generation control (AGC\(^2\)) systems.
- Limits due to sharing capacity between different types of FCAS and energy.

In order to understand this document, readers should be familiar with the relevant inputs to NEMDE, such as FCAS offer trapeziums, offer ramp rates, AGC ramp rates, and AGC enablement limits. This document uses many terms that have meanings defined in the National Electricity Rules (NER). The NER meanings are adopted unless otherwise specified.

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\(^2\) AGC limits are also referred to as Supervisory Control and Data Acquisition (SCADA) limits or AGC SCADA limits.
2. STRUCTURE OF AN FCAS OFFER

Under the Rules, an FCAS offer comprises:

- Ten price bands, each with a band price ($/MWh) and band availability (MW). Prices are defined for a trading day, and MW quantities are defined for each trading interval of a trading day.
- The following technical limits on the provision (or enabling) of that FCAS:
  - Enablement Min (MW)
  - Low Breakpoint (MW)
  - High Breakpoint (MW)
  - Enablement Max (MW)
  - Max Availability (MW)

Together these form an FCAS offer trapezium, as illustrated in Figure 1. The FCAS offer trapezium defines the “as offered” frequency response capability of the FCAS provider in relation to its active power generation or consumption levels. Power generation or consumption levels are shown on the horizontal axis (as energy), and the frequency response capability is shown on the vertical axis (as FCAS).

Figure 1: FCAS offer trapezium – energy and FCAS capability relationship

The technical limits submitted as part of an FCAS offer must be within the bounds of the technical envelope specified during registration of that provider for that FCAS.

If a provider is registered for FCAS only, and does not participate in the energy market as a scheduled or semi-scheduled generating unit or scheduled load, then its FCAS offer trapezium would be a vertical line, as shown in Figure 2. In this case its frequency response capability in central dispatch is independent of its energy level because there is no energy dispatched by NEMDE.
Figure 2: FCAS offer trapezium – FCAS provision only

<table>
<thead>
<tr>
<th>FCAS (MW)</th>
<th>Max Availability (Offer)</th>
<th>Energy (MW)</th>
</tr>
</thead>
</table>
3. APPLICATION OF AN FCAS OFFER

The maximum FCAS that can be enabled is bounded by the FCAS offer trapezium for that service.

For example, if a unit is dispatched in the energy market between its Low Breakpoint and High Breakpoint, the maximum available FCAS that can be enabled equals its Max Availability, as shown by the vertical red line in Figure 3.

If a unit is dispatched in the energy market between its Enablement Min and Low Breakpoint, the available FCAS is bound by the left-hand-side lower trapezium slope, as shown in Figure 4.

If a unit is dispatched in the energy market between its High Breakpoint and Enablement Max, the available FCAS is bound by the right-hand-side upper trapezium slope, as shown in Figure 5.

If a unit is operating below its Enablement Min or above its Enablement Max, the available FCAS that can be enabled is zero.

Figure 3: Energy target between breakpoints

![Figure 3: Energy target between breakpoints](image)

Figure 4: Energy target between Low Breakpoint and Enablement Min

![Figure 4: Energy target between Low Breakpoint and Enablement Min](image)
**Figure 5: Energy Target between High Breakpoint and Enablement Max**

<table>
<thead>
<tr>
<th>Enablement Min</th>
<th>Low Breakpoint</th>
<th>High Breakpoint</th>
<th>Enablement Max</th>
</tr>
</thead>
<tbody>
<tr>
<td>Max Availability</td>
<td>Total Cleared Energy</td>
<td>Available FCAS</td>
<td>Energy Dispatch Target</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>FCAS (MW)</th>
<th>Energy (MW)</th>
</tr>
</thead>
<tbody>
<tr>
<td>Low Breakpoint</td>
<td>High Breakpoint</td>
</tr>
<tr>
<td>Enablement Min</td>
<td>Enablement Max</td>
</tr>
<tr>
<td>Total Cleared Energy</td>
<td>Energy Dispatch Target</td>
</tr>
</tbody>
</table>
4. SCALING THE FCAS OFFER WITHIN TECHNICAL LIMITS

The bounds of an FCAS offer trapezium used by NEMDE may be more restrictive than those submitted in the FCAS offer from a provider, depending on the technical limits of the plant at the time.

- For regulating services, NEMDE scales the FCAS offer trapezium to within the telemetered AGC enablement and availability limits. This scaling does not apply to contingency services.
- For semi-scheduled units, the FCAS offer trapezium is also scaled to within the unconstrained intermittent generation forecast (UIGF) for both regulating and contingency services.

This process is called FCAS trapezium scaling. If no scaling is applied, the FCAS trapezium used by NEMDE is the same as the offered FCAS trapezium.

Note that no FCAS trapezium scaling is applied to contingency FCAS offers from scheduled units. For example, if an FCAS provider reduces the maximum availability of their unit in the energy market to below the Enablement Max of any of their FCAS offers, NEMDE does not automatically scale the Enablement Max (and High Breakpoint) of those FCAS offers.

FCAS trapezium scaling occurs in a pre-processing step within NEMDE before optimisation occurs.

4.1 Scaling for AGC enablement limits

NEMDE uses the most restrictive of offer enablement limits and AGC enablement limits for regulating services. If the AGC limits are more restrictive than the offer enablement limits, NEMDE scales the offer trapezium by making the AGC enablement limits the effective enablement limits, and adjusting the trapezium break points to maintain the trapezium angles. If the offer enablement limits are more restrictive than the AGC limits, this scaling has no impact and the offer trapezium enablement limits are used in NEMDE. If the AGC enablement limit is zero or absent, no scaling is applied.

Scaling by AGC enablement limits is shown in Figure 6.

Figure 6: FCAS trapezium scaling by AGC enablement limits
4.2 Scaling for AGC ramp rates

NEMDE uses the more restrictive of offer Max Availability and AGC ramping capability for regulating service maximum availability. The AGC ramping capability is calculated as the AGC ramp rate multiplied by the interval time period. For example, if the AGC ramp rate is 5MW/min, the AGC ramping capability for a 5-minute dispatch interval is 25MW (i.e. 5MW/min x 5 minutes = 25MW). If the AGC ramping capability is more restrictive than the offer Max Availability, NEMDE scales the trapezium by using the AGC ramping capability as the effective Max Availability, and adjusts the trapezium break points to maintain the trapezium angles. If the AGC ramping capability is higher than the offer Max Availability, the scaling has no impact. If the AGC ramp rate is zero or absent, no scaling is applied.

Scaling by AGC ramp rates is shown in Figure 7.

Figure 7: FCAS trapezium scaling by AGC ramp rates

4.3 Scaling for UIGF

NEMDE uses the more restrictive of offer Enablement Max and the UIGF for all FCAS services provided by semi-scheduled units. If the UIGF is more restrictive than the offer Enablement Max, NEMDE scales the offer trapezium by making the UIGF the effective maximum enablement limit, and adjusting the trapezium upper break point to maintain the trapezium angles. If the offer enablement maximum limit is more restrictive than the UIGF, this scaling has no impact.

FCAS trapezium scaling by UIGF is shown in Figure 8.
4.4 Application of FCAS Trapezium Scaling in Dispatch, Pre-dispatch and 5-minute Pre-dispatch

The application of FCAS trapezium scaling discussed in sections 4.1 to 4.3 may cause a “shrinkage” of the original FCAS offer trapezium, as shown in Figure 9.

Table 1 summarises the range of intervals over which FCAS trapezium scaling applies in the Dispatch, Pre-dispatch and 5-minute Pre-dispatch processes.
Table 1: Intervals over which FCAS trapezium scaling applies

<table>
<thead>
<tr>
<th>Constraints</th>
<th>Intervals to which the constraint applies</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>Dispatch</td>
</tr>
<tr>
<td>Scaling for AGC enablement limits</td>
<td>All</td>
</tr>
<tr>
<td>Scaling for AGC ramp rates</td>
<td>All</td>
</tr>
<tr>
<td>Scaling for UIGF</td>
<td>All</td>
</tr>
</tbody>
</table>

The FCAS trapezium that NEMDE uses for the optimisation process is the scaled (effective) trapezium.
5. **PRE-CONDITIONS FOR ENABLING FCAS**

After FCAS trapezium scaling, a scheduled or semi-scheduled generating unit or scheduled load is considered for enablement for a particular FCAS in NEMDE if the following conditions are met:

- The maximum availability offered for the service is greater than zero.
  
  \[ FCAS \text{ Max Availability} > 0 \]

- At least one of the offer price bands has a capacity greater than zero for the service.

- The energy availability is greater than or equal to the FCAS trapezium enablement minimum of the service.
  
  \[ Energy \text{ Max Availability} \geq FCAS \text{ Enablement Min} \]

- The FCAS trapezium enablement maximum of the service is greater than or equal to zero.
  
  \[ FCAS \text{ Enablement Max} \geq 0 \]

- The unit is initially operating between the FCAS trapezium enablement minimum and maximum of the service.
  
  \[ FCAS \text{ Enablement Min} \leq Initial \text{ MW} \leq FCAS \text{ Enablement Max} \]

One consequence of this pre-condition is that units operating at an energy level less than the Enablement Min or more than the Enablement Max of an FCAS trapezium cannot be enabled for that FCAS. This phenomenon is referred to as “stranded outside the FCAS trapezium”.

- In pre-dispatch, if the unit is energy constrained (i.e. the daily energy constraint in the bid is greater than zero), the remaining energy for the day must be above the FCAS trapezium enablement minimum for the service.
  
  \[ 2 \times \text{remaining energy available} > FCAS \text{ Enablement Min} \]

In addition to the above conditions, for Dispatch and the first interval of Pre-dispatch and 5-minute Pre-dispatch, regulating FCAS is enabled only if the following condition is met:

- AGC Status is “On”.


6. JOINT ENERGY AND FCAS CONSTRAINTS

After FCAS trapezium scaling, and if a scheduled or semi-scheduled generating unit or scheduled load is considered for enablement for a particular FCAS in NEMDE, further constraints will be imposed within NEMDE to ensure that the unit can physically deliver all the energy for which it has been dispatched, and all the FCAS for which it has been enabled.

An FCAS trapezium defines the maximum frequency response that a unit can provide for that particular service only. The actual maximum response may be less than the level defined by the trapezium if the unit is providing multiple services.

To ensure that the combined energy dispatch and FCAS enablement is within a unit’s technical capability, NEMDE creates intrinsic “joint ramping”, “joint capacity”, and “energy and regulating FCAS capacity” constraints to represent the unit’s joint ramping and capacity capabilities.

- The joint ramping constraint is applied to regulating services and ensures that the combined amount of increase or decrease of energy and regulating services is within the real-time AGC ramp rates telemetered from the unit.
- The joint capacity constraint is applied to each contingency service and affects both regulating and contingency services. It ensures that the maximum amount of contingency service that a unit can provide is offset by the amounts of regulating service for which the unit is enabled and energy for which it is dispatched.
- The energy and regulating FCAS capacity constraint is applied to regulating services and ensures that the maximum amount of regulating FCAS that a unit can provide is offset by the amount of energy for which it is dispatched. This is similar to the joint capacity constraint but involves only regulating FCAS and energy.

These NEMDE intrinsic constraints as a group are referred to as “unit FCAS constraints”. Table 2 summarises the application of the unit FCAS constraints to regulating and contingency services.

<table>
<thead>
<tr>
<th>Table 2: Application of unit FCAS constraints</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>Joint ramping constraint</strong></td>
</tr>
<tr>
<td>Applied</td>
</tr>
<tr>
<td><strong>Joint capacity constraint</strong></td>
</tr>
<tr>
<td><strong>Energy and regulating FCAS capacity constraint</strong></td>
</tr>
</tbody>
</table>

NEMDE applies the unit FCAS constraints simultaneously during the optimisation process and searches for the optimum solution that satisfies all constraints concurrently.

6.1 Joint ramping constraints

If a unit’s energy dispatch is already constrained at its telemetered AGC ramp rate, it leaves no spare ramping capability for frequency regulation in the same direction. NEMDE co-optimises the joint dispatch of energy and enablement of regulating service from the unit so that, if required, the unit’s AGC is physically able to deliver both, up to the unit’s relevant telemetered AGC ramp rate limit.

NEMDE applies joint ramping constraints to ensure that any combined change in energy output and regulating service delivery is within the AGC ramp rates. Joint ramping constraints are based on the

3 AEMO’s AGC cannot physically dispatch a unit beyond its telemetered AGC ramp rate limits.
initial telemetered AGC ramping capability at the initial generation or consumption level for each unit, and are applied if a unit has an energy offer, is enabled for regulating services, and the AGC ramp up or down rate is greater than zero. The joint ramping constraint equations are:

\[
\text{Energy Dispatch Target + Raise Regulating FCAS Target} \leq \text{Initial MW + SCADA Ramp Up Capability}^4
\]

if \( \text{SCADA Ramp Up Rate} > 0 \)

\[
\text{Energy Dispatch Target - Lower Regulating FCAS Target} \geq \text{Initial MW - SCADA Ramp Down Capability}
\]

if \( \text{SCADA Ramp Down Rate} > 0 \)

where

\[
\text{SCADA Ramp Up Capability} = \text{SCADA Ramp Up Rate} \times \text{Time Period}
\]

\[
\text{SCADA Ramp Down Capability} = \text{SCADA Ramp Down Rate} \times \text{Time Period}
\]

Initial MW is the output or consumption of the unit at the beginning of the dispatch interval.

Figure 10 depicts a joint ramping constraint applied to a typical regulating raise service trapezium with a 45° upper slope. As the constraint also has a 45° slope, it runs parallel to the right-hand-side trapezium slope. It shows how the constraint reduces the feasible solution area by truncating the area under the upper trapezium slope.

Figure 11 and Figure 12 show how the feasible solution area is truncated by a joint ramping constraint if the trapezium does not have a 45° upper slope.

**Figure 10: Joint ramping constraint – 45° angle upper slope**

\[
\text{AGC Ramping Capability}
\]

\[
\text{Energy (MW)}
\]

---

* The constraint equations in this document are simplified versions of the NEMDE constraints and do not include constraint surplus and deficit terms. Terms in blue are “dispatchable entities” and their values are determined by NEMDE and published as part of the NEMDE solution.
Figure 11: Joint ramping constraint – steep upper slope

Figure 12: Joint ramping constraint – shallow upper slope

Similar diagrams can be drawn for the regulating lower service. For the regulating lower service, the joint ramping constraint would truncate the feasible solution area under the left-hand-side trapezium slope.

6.2 Joint capacity constraints

The maximum contingency service response that a unit can physically provide following a contingency event may be reduced if the unit has already used its capacity to provide a regulation frequency response. NEMDE applies joint capacity constraints to co-optimise the dispatch of energy and the enablement of regulating services and contingency services from a unit to avoid infeasible dispatch outcomes in which a unit is enabled for both regulating and contingency services but unable to fully deliver both following a contingency event.

Figure 13 shows an example of the co-optimisation of energy, regulating FCAS and contingency FCAS. For a particular energy target, the combined availability of regulating and contingency services is limited by the relevant joint capacity constraint, shown as a solid red line. The feasible solution space for a
The given energy target is the area underneath the red line on the contingency FCAS – regulating FCAS plane, and the optimum solution lies on the red line.

**Figure 13: Joint capacity constraint in 3D**

The 3D relationship illustrated in Figure 13 can be simplified by recognising that energy and the regulating services have a one-to-one relationship. In other words, a 1MW reduction in energy output can potentially increase a generating unit’s regulating raise service availability by 1 MW and decrease its regulating lower service availability by 1 MW. Similarly, a 1MW increase in energy output can potentially reduce its regulating raise service availability by 1 MW and increase its regulating lower service availability by 1 MW.

This relationship allows the 3D diagram to be simplified in 2D, as shown in Figure 14. Note that the regulating FCAS trapezium has been removed in the 2D diagram, and that the regulating FCAS target is shown on the horizontal axis along with the energy target. A joint capacity constraint now runs parallel to the contingency FCAS trapezium slope.

---

5 Energy and regulating FCAS can be drawn on the same scale and the same plane because of their one-to-one relationship.
Joint capacity constraints are created for all units with an energy offer and which are enabled for a contingency service. One set of constraints is created for each contingency service (fast raise, slow raise, delayed raise, fast lower, slow lower, or delayed lower) for which the unit is enabled. The joint capacity constraint equations for each type of contingency FCAS are:

\[
\text{Energy Dispatch Target} + \text{Upper Slope Coeff} \times \text{Contingency FCAS Target} \\
+ \left[ \text{Raise Regulation FCAS enablement status} \right] \times \text{Raise Regulating FCAS Target} \\
\leq \text{EnablementMax}^6
\]

\[
\text{Energy Dispatch Target} - \text{Lower Slope Coeff} \times \text{Contingency FCAS Target} \\
- \left[ \text{Lower Regulation FCAS enablement status} \right] \times \text{Lower Regulating FCAS Target} \\
\geq \text{EnablementMin}^7
\]

where

\[^6\text{To ensure that the sum of the contingency and regulating raise service availabilities are capped by the contingency service trapezium when operating on the upper slope of that trapezium.}\]

\[^7\text{To ensure that the sum of the contingency and regulating lower service availabilities are capped by the contingency service trapezium when operating on the lower slope of that trapezium.}\]
The joint capacity constraint equations are depicted in Figure 15 and Figure 16.

**Figure 15: Joint capacity constraint equation – energy dispatch target + upper slope x contingency FCAS target + regulating raise FCAS target ≤ Enablement Max**

\[
Upper \ Slope \ Coeff = \frac{EnablementMax - HighBreakPoint}{MaxAvail}
\]

\[
Lower \ Slope \ Coeff = \frac{LowBreakPoint - EnablementMin}{MaxAvail}
\]

\[\text{[Raise Regulation FCAS enablement status]} = 1 \text{ if the regulating raise service is enabled for the unit, otherwise 0.}\]

\[\text{[Lower Regulation FCAS enablement status]} = 1 \text{ if the regulating lower service is enabled for the unit, otherwise 0.}\]

One consequence of these constraints is that the energy dispatch target is bound by the Enablement Min and the Enablement Max when a unit is enabled for contingency FCAS. This phenomenon is referred to as “trapped within the FCAS trapezium”.

**Figure 16: Joint capacity constraint equation – energy dispatch target – lower slope x contingency FCAS target – lower regulating FCAS target ≥ Enablement Min**
6.3 Energy and regulating FCAS capacity constraint

NEMDE applies energy and regulating FCAS capacity constraints to ensure that the dispatch of energy and enablement of regulating services is co-optimised within the bounds specified by the regulating service trapezium. This prevents infeasible dispatch outcomes in which a unit is enabled for regulating FCAS but unable to fully deliver it.

Energy and regulating FCAS capacity constraints are created for all units with an energy offer and which are enabled for regulating services. The energy and regulating FCAS capacity constraint equations are:

\[
\text{Energy Dispatch Target} + \text{Upper Slope Coeff} \times \text{Regulating FCAS Target} \leq \text{EnablementMax}^8
\]
\[
\text{Energy Dispatch Target} - \text{Lower Slope Coeff} \times \text{Regulating FCAS Target} \geq \text{EnablementMin}^9
\]

where

\[
\text{Upper Slope Coeff} = \frac{\text{EnablementMax} - \text{HighBreakPoint}}{\text{MaxAvail}}
\]
\[
\text{Lower Slope Coeff} = \frac{\text{LowBreakPoint} - \text{EnablementMin}}{\text{MaxAvail}}
\]

These energy and regulating FCAS capacity constraint equations are depicted in Figure 17. The constraints simply enforce the limits specified by the regulating FCAS trapezium slopes.

**Figure 17: Energy and regulating FCAS capacity constraint**

One consequence of these constraints is that the energy dispatch target is bound by the Enablement Min and the Enablement Max when a unit is enabled for regulating FCAS. As with contingency FCAS, this phenomenon is referred to as “trapped within the FCAS trapezium”.

6.4 Application of unit FCAS constraints in Dispatch, Pre-dispatch and 5-minute Pre-dispatch

Table 3 summarises the range of intervals over which the unit FCAS constraints apply in the Dispatch, Pre-dispatch and 5-minute Pre-dispatch processes.

---

8 To ensure that the regulating FCAS availability is capped by the regulating FCAS trapezium when operating on the upper slope of the trapezium.
9 To ensure that the regulating FCAS availability is capped by the regulating FCAS trapezium when operating on the lower slope of the trapezium.
### Table 3: Intervals over which unit FCAS constraints apply

<table>
<thead>
<tr>
<th>Constraints</th>
<th>Intervals to which the constraint applies</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>Dispatch</td>
</tr>
<tr>
<td>Joint ramping constraint</td>
<td>All(^{10})</td>
</tr>
<tr>
<td>Joint capacity constraint</td>
<td>All</td>
</tr>
<tr>
<td>Energy and regulating FCAS capacity constraint</td>
<td>All</td>
</tr>
</tbody>
</table>

\(^{10}\) Excludes the 1\(^{st}\) Pass Fast Start Commitment and 2\(^{nd}\) Pass Dispatch solves for Fast Start units initially in Fast Start Inflexibility Modes 0, 1 or 2.
7. **FCAS AVAILABILITY**

If a unit is enabled for a particular FCAS, then its FCAS availability is calculated by finding the most restrictive constraint that limits the unit’s frequency response capability at a given energy target.

FCAS availability is based on energy dispatch targets and the amounts of FCAS enabled, rather than the quantities of FCAS offered into the market, because FCAS trapezium scaling, the pre-conditions for FCAS enablement, and unit FCAS constraints can all restrict the amounts of FCAS that can feasibly be delivered by an FCAS provider.

The FCAS availability for a unit at a given energy target is the maximum amount of the service that the unit can provide when it is fully delivering the amounts of all other services for which it is enabled at that energy target. For example, the regulating service availability of a unit in a particular direction (raise or lower) is the maximum regulating response that the unit is able to deliver when it is generating or consuming at its energy target and fully delivering any enabled contingency service in the same direction. Conversely, the contingency service availability of a unit in a particular direction is the maximum contingency response that the unit is able to deliver when it is generating or consuming at its energy target and fully delivering any enabled regulating service in the same direction.

The FCAS availability for a unit for a particular FCAS is set to 0 MW if the unit cannot be enabled for that service due to the failure of one or more of the pre-conditions specified in Section 5.

AEMO must also publish actual quantities of each type of FCAS every year.\(^\text{11}\) AEMO meets this requirement by publishing the maximum available quantity of each FCAS on a region-aggregate basis after each Dispatch and Pre-dispatch run, and publishing the maximum available quantity of each FCAS on a per-unit basis at the end of each trading day.\(^\text{12}\) The FCAS availability calculation is performed as a post-processing step at the time of loading the NEMDE solution into the Electricity Market Management System (EMMS) database.

7.1 **Calculation of FCAS availability**

If a unit’s Initial MW is outside its enablement limits, then its FCAS availability is 0 MW because the unit will not be enabled for FCAS. Otherwise, the FCAS availability for a given energy target is set by the most restrictive constraint. There are five constraint types that can limit FCAS availability. These constraint types are marked from 1 to 5 below for later reference.

**FCAS Availability =**

\[
\text{MINIMUM of } \left[ \begin{array}{l}
\text{FCAS availability set by the FCAS trapezium Max Availability (1)} \\
\text{FCAS availability set by the FCAS trapezium upper slope (2)} \\
\text{FCAS availability set by the FCAS trapezium lower slope (3)} \\
\text{FCAS availability set by the joint capacity constraint (4)} \\
\text{FCAS availability set by the joint ramping constraint – for Regulating services only (5)} \\
\end{array} \right]
\]

where the FCAS trapezium is the scaled (effective) FCAS trapezium from Section 4. For the regulating service availability calculation, there can be multiple type 4 joint capacity constraints because a joint capacity constraint is created for each contingency service for which the unit is enabled.

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\(^\text{11}\) Required under clause 3.13.4A(b1) of the Rules.

\(^\text{12}\) Unit FCAS availability is provided confidentially to the relevant participant after each Dispatch and Pre-dispatch run. This information is made public at the end of each trading day.
Figure 18 is an example showing how the constraints are applied. In this particular example, the constraint resulting in the most restrictive FCAS availability for the given energy target is the joint capacity constraint.

**Figure 18: FCAS availability**

FCAS availability for each FCAS can be calculated using the formula below. The formula incorporates the FCAS trapezium scaling. For each limit equation, the corresponding constraint type is marked from 1 to 5.

Note that:

- Limit #1, #2 and #3 define the FCAS trapezium.
- Limit #4, #5 and #6 reflect the joint capacity constraint.
- Limit #7 reflects the joint ramping constraint – this constraint applies only to regulating services.
- If $Upper\ Slope\ Coeff = 0$ or $Lower\ Slope\ Coeff = 0$ then the corresponding availability limit is ignored.
Regulating Raise FCAS Availability =
MINIMUM of [
1. Effective RReg FCAS MaxAvail ................................................................. 1
2. (Effective RReg EnablementMax - Energy Target) / Upper Slope Coeff RReg   ....... 2
3. (Energy Target - Effective RReg EnablementMin) / Lower Slope Coeff RReg .......... 3
4. Offer R6 EnablementMax - Energy Target - (Upper Slope Coeff R6 x R6 Target) ....... 4
5. Offer R60 EnablementMax - Energy Target - (Upper Slope Coeff R60 x Raise60 Target) ..... 4
6. Offer R5 EnablementMax - Energy Target - (Upper Slope Coeff R5 x R5 Target) ........ 4
7. JointRampRaiseMax - Energy Target ............................................................. 5
]

Regulating Lower FCAS Availability =
MINIMUM of [
1. Effective LReg FCAS MaxAvail ................................................................. 1
2. (Effective LReg EnablementMax - Energy Target) / Upper Slope Coeff LReg ........... 2
3. (Energy Target - Effective LReg EnablementMin) / Lower Slope Coeff LReg .......... 3
4. Energy Target – Offer L6 EnablementMin - (Lower Slope Coeff L6 x L6 Target) ....... 4
5. Energy Target – Offer L60 EnablementMin - (Lower Slope Coeff L60 x L60 Target) ...... 4
6. Energy Target – Offer L5 EnablementMin - (Lower Slope Coeff L5 x L5 Target) ........ 4
7. Energy Target – JointRampLowerMin ............................................................ 5
]

Contingency Raise FCAS Availability for service Rxx =
MINIMUM of [
1. Offer Rxx FCAS MaxAvail ............................................................................. 3
2. (Offer Rxx EnablementMax - Energy Target) / Upper Slope Coeff Rxx ................. 2
3. (Energy Target - Offer Rxx EnablementMin) / Lower Slope Coeff Rxx ................... 3
4. (Offer Rxx EnablementMax - Energy Target - RReg Target) / Upper Slope Coeff Rxx ...... 4
]

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Contingency Lower FCAS Availability for service Lxx =

MINIMUM of [ 

1. \( \text{Offer Lxx FCAS MaxAvail} \) .......................................................... 1 

2. \( \frac{(\text{Offer Lxx EnablementMax} - \text{Energy Target})}{\text{Upper Slope Coeff Lxx}} \) ................. 2 

3. \( \frac{(\text{Energy Target} - \text{Offer Lxx EnablementMin})}{\text{Lower Slope Coeff Lxx}} \) ................. 3 

4. \( \frac{(\text{Energy Target} - \text{Offer Lxx EnablementMin} - \text{LReg Target})}{\text{Lower Slope Coeff Lxx}} \) ...... 4 

] 

where

\( \text{Effective RReg FCAS MaxAvail} = \text{Min} (\text{Offer RReg FCAS MaxAvail}, \text{AGC Ramp Up Rate} \times \text{Time Period}) \)

\( \text{Effective RReg EnablementMax} = \text{Min} (\text{Offer RReg EnablementMax}, \text{AGC Upper Limit}) \)

\( \text{Effective RReg EnablementMin} = \text{Max} (\text{Offer RReg EnablementMin}, \text{AGC Lower Limit}) \)

\( \text{Effective LReg FCAS MaxAvail} = \text{Min} (\text{Offer LReg FCAS MaxAvail}, \text{AGC Ramp Up Rate} \times \text{Time Period}) \)

\( \text{Effective LReg EnablementMax} = \text{Min} (\text{Offer LReg EnablementMax}, \text{AGC Upper Limit}) \)

\( \text{Effective LReg EnablementMin} = \text{Max} (\text{Offer LReg EnablementMin}, \text{AGC Lower Limit}) \)

\( \text{JointRampRaiseMax} = \text{Initial MW} + (\text{AGC Ramp Up Rate} \times \text{Time Period}) \)

\( \text{JointRampLowerMin} = \text{Initial MW} - (\text{AGC Ramp Down Rate} \times \text{Time Period}) \)

\( \text{Lower Slope Coeff \( xx \)} = \frac{\text{Offer \( xx \) LowBreakPoint} - \text{Offer \( xx \) EnablementMin}}{\text{Offer \( xx \) MaxAvail}} \)

\( \text{Upper Slope Coeff \( xx \)} = \frac{\text{Offer \( xx \) EnablementMax} - \text{Offer \( xx \) HighBreakPoint}}{\text{Offer \( xx \) MaxAvail}} \)

(When calculating the Lower Slope Coeff and Upper Slope Coeff for regulating FCAS, the offer trapezium parameters produce the same outcome as the effective trapezium parameters because the trapezium angles are maintained during FCAS trapezium scaling.)

Examples of FCAS availability calculation are provided in Appendix A.
## 7.2 Publication of FCAS availability

Table 4 summarises the content and timing of FCAS availability information published to the EMMS Data Model.

**Table 4: FCAS Availability publication**

<table>
<thead>
<tr>
<th>Column name</th>
<th>Table name</th>
<th>Information</th>
<th>Publication time</th>
</tr>
</thead>
<tbody>
<tr>
<td>Raise6SecActualAvailability</td>
<td>DispatchLoad</td>
<td>Unit FCAS availability for dispatch</td>
<td>Available to the relevant participant every 5-minutes.</td>
</tr>
<tr>
<td>Raise60SecActualAvailability</td>
<td>DispatchRegionSum</td>
<td>Regional FCAS availability for dispatch</td>
<td>Every 5-minutes</td>
</tr>
<tr>
<td>Raise5MinActualAvailability</td>
<td>PredispatchLoad</td>
<td>Unit FCAS availability for pre-dispatch</td>
<td>Available to the relevant participant every 30-minutes.</td>
</tr>
<tr>
<td>RaiseRegActualAvailability</td>
<td>PredispatchRegionSum</td>
<td>Regional FCAS availability for pre-dispatch</td>
<td>Every 30-minutes</td>
</tr>
<tr>
<td>Lower6SecActualAvailability</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Lower60SecActualAvailability</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Lower5MinActualAvailability</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>LowerRegActualAvailability</td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>
APPENDIX A. EXAMPLES – FCAS AVAILABILITY

A.1 Base case

Assume the following base case conditions:

- Region Energy price = $30/MWh
- Region FCAS prices = $3/MWh for all FCAS

GEN01 unit is a slow-start generating unit, with all energy offered at $10/MWh, any FCAS offered at $1/MWh, and the following offer profile:

<table>
<thead>
<tr>
<th>GEN01</th>
<th>Max Availability (MW)</th>
<th>Ramp Up Rate (MW/min)</th>
<th>Ramp Down Rate (MW/min)</th>
<th>Enablement Minimum (MW)</th>
<th>Low Break Point (MW)</th>
<th>High Break Point (MW)</th>
<th>Enablement Maximum (MW)</th>
</tr>
</thead>
<tbody>
<tr>
<td>Energy</td>
<td>690</td>
<td>5</td>
<td>5</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Raise 6 Sec</td>
<td>66</td>
<td></td>
<td></td>
<td>234</td>
<td>234</td>
<td>624</td>
<td>690</td>
</tr>
<tr>
<td>Raise 60 Sec</td>
<td>66</td>
<td></td>
<td></td>
<td>234</td>
<td>234</td>
<td>575</td>
<td>690</td>
</tr>
<tr>
<td>Raise 5 Min</td>
<td>66</td>
<td></td>
<td></td>
<td>290</td>
<td>300</td>
<td>624</td>
<td>690</td>
</tr>
<tr>
<td>Regulating Raise</td>
<td>100</td>
<td></td>
<td></td>
<td>300</td>
<td>300</td>
<td>590</td>
<td>680</td>
</tr>
<tr>
<td>Lower 6 Sec</td>
<td>66</td>
<td></td>
<td></td>
<td>234</td>
<td>300</td>
<td>690</td>
<td>690</td>
</tr>
<tr>
<td>Lower 60 Sec</td>
<td>66</td>
<td></td>
<td></td>
<td>234</td>
<td>300</td>
<td>690</td>
<td>690</td>
</tr>
<tr>
<td>Lower 5 Min</td>
<td>76</td>
<td></td>
<td></td>
<td>290</td>
<td>366</td>
<td>690</td>
<td>690</td>
</tr>
<tr>
<td>Regulating Lower</td>
<td>100</td>
<td></td>
<td></td>
<td>300</td>
<td>400</td>
<td>690</td>
<td>690</td>
</tr>
</tbody>
</table>

Real-time SCADA telemetry gives the following values for GEN01:

<table>
<thead>
<tr>
<th>GEN01 SCADA</th>
<th>GEN01 SCADA values</th>
</tr>
</thead>
<tbody>
<tr>
<td>AGC Ramp Up Rate</td>
<td>3 MW/min</td>
</tr>
<tr>
<td>AGC Ramp Down Rate</td>
<td>2 MW/min</td>
</tr>
<tr>
<td>AGC Lower Limit</td>
<td>280 MW</td>
</tr>
<tr>
<td>AGC Upper Limit</td>
<td>670 MW</td>
</tr>
<tr>
<td>AGC Status</td>
<td>ON</td>
</tr>
</tbody>
</table>
Consequently, FCAS trapezium scaling during pre-processing gives the following parameters for regulating FCAS from GEN01:

<table>
<thead>
<tr>
<th>GEN01 FCAS Parameter</th>
<th>Regulating Raise</th>
<th>Regulating Lower</th>
</tr>
</thead>
<tbody>
<tr>
<td>Effective Max Availability</td>
<td>15</td>
<td>10</td>
</tr>
<tr>
<td>Effective Enablement Max</td>
<td>670</td>
<td>670</td>
</tr>
<tr>
<td>Effective Enablement Min</td>
<td>300</td>
<td>300</td>
</tr>
<tr>
<td>Effective Low Break Point</td>
<td>300</td>
<td>310</td>
</tr>
<tr>
<td>Effective High Break Point</td>
<td>656.5</td>
<td>670</td>
</tr>
</tbody>
</table>

A.2 Scenario 1: Regulating and 5-minute FCAS available

Initial MW = 450 MW

Only RaiseReg, Raise5Min, LowerReg and Lower5Min FCAS offered

The Initial MW of 450 MW is between the enablement limits of all the offered FCAS so both the joint ramping and joint capacity constraints are automatically invoked by NEMDE for raise and lower FCAS services.

Joint Ramping Constraints (section 6.1):

\[
\text{Energy Target} + \text{RaiseReg Target} \leq \text{JointRampRaiseMax}
\]

\[
\text{Energy Target} - \text{LowerReg Target} \geq \text{JointRampLowerMin}
\]

where

\[
\text{JointRampRaiseMax} = \text{Initial MW} + (\text{AGC Ramp Up Rate} \times 5)
\]

\[
= 450 + (3 \times 5)
\]

\[
= 465 \text{ MW}
\]

\[
\text{JointRampLowerMin} = \text{Initial MW} - (\text{AGC Ramp Down Rate} \times 5)
\]

\[
= 450 - (2 \times 5)
\]

\[
= 440 \text{ MW}
\]

Joint Capacity Constraints (Section 6.2):

\[
\text{Energy Target} + \text{Upper Slope Coeff}_{R5MI} \times \text{Raise5Min Target} + \text{RaiseReg Target} \leq \text{Raise5Min Enablement Max}
\]

\[
\text{Energy Target} + \text{Upper Slope Coeff}_{L5MI} \times \text{Lower5Min Target} + \text{RaiseReg Target} \leq \text{Lower5Min Enablement Max}
\]

\[
\text{Energy Target} - \text{Lower Slope Coeff}_{R5MI} \times \text{Raise5Min Target} - \text{LowerReg Target} \geq \text{Raise5Min Enablement Min}
\]

\[
\text{Energy Target} - \text{Lower Slope Coeff}_{L5MI} \times \text{Lower5Min Target} - \text{LowerReg Target} \geq \text{Lower5Min Enablement Min}
\]

where
**FCAS MODEL IN NEMDE**

*Raise5min Enablement Max = 690 MW*

*Lower5min Enablement Max = 690 MW*

*Raise5min Enablement Min = 290 MW*

*Lower5min Enablement Min = 290 MW*

**Upper Slope Coef** = \( \frac{(\text{Raise5min Enablement Max} - \text{Raise5min High Break Point})}{\text{Raise5min Max Availability}} \) = \( \frac{(690 - 624)}{66} \) = 1

**Upper Slope Coef** = \( \frac{(\text{Lower5min Enablement Max} - \text{Lower5min High Break Point})}{\text{Lower5min Max Availability}} \) = \( \frac{(690 - 690)}{76} \) = 0

**Lower Slope Coef** = \( \frac{(\text{Raise5min Low Break Point} - \text{Raise5min Enablement Min})}{\text{Raise5min Max Availability}} \) = \( \frac{(300 - 290)}{66} \) = 0.152

**Lower Slope Coef** = \( \frac{(\text{Lower5min Low Break Point} - \text{Lower5min Enablement Min})}{\text{Lower5min Max Availability}} \) = \( \frac{(366 - 290)}{76} \) = 1

Substituting into the joint capacity constraints:

\[
\begin{align*}
\text{Energy Target} + \text{Raise5min Target} + \text{RaiseReg Target} & \leq 690 \\
\text{Energy Target} + \text{RaiseReg Target} & \leq 690 \\
\text{Energy Target} - 0.152 * \text{Raise5min Target} - \text{LowerReg Target} & \geq 290 \\
\text{Energy Target} - \text{Lower5min Target} - \text{LowerReg Target} & \geq 290
\end{align*}
\]

**GEN01 Solution**

<table>
<thead>
<tr>
<th>Quantity</th>
<th>Value</th>
</tr>
</thead>
<tbody>
<tr>
<td>Energy target</td>
<td>465 MW</td>
</tr>
<tr>
<td>RaiseReg target</td>
<td>0 MW</td>
</tr>
<tr>
<td>Raise5Min target</td>
<td>66 MW</td>
</tr>
<tr>
<td>LowerReg target</td>
<td>10 MW</td>
</tr>
<tr>
<td>Lower5Min target</td>
<td>76 MW</td>
</tr>
</tbody>
</table>

GEN01 unit's energy target is binding at the *JointRampRaiseMax* of the unit's joint ramping constraints, resulting in a RaiseReg target of zero. The full amount of LowerReg, Lower5Min and Raise5Min can be dispatched.

**A.3 Scenario 2: Regulating FCAS unavailable**

**Initial MW = 680 MW**

The *Initial MW* of 680 MW is outside the regulating FCAS enablement limits, so the unit cannot be enabled for regulating FCAS. (The unit is "stranded".) In this case the pre-processing logic creates neither joint capacity constraints nor joint ramping constraints.

This unit is reported as "stranded" for regulating FCAS.
A.4 Scenario 3: Availability calculation

The following set of FCAS availability calculations is based on Scenario 1, with some changes to the GEN01 unit targets.

Assumptions:

- Initial MW = 450 MW
- Energy target = 455 MW
- RaiseReg target = 10 MW
- LowerReg target = 10 MW
- Raise5Min target = 50 MW
- Lower5Min target = 50 MW

Substituting the unit energy and FCAS targets to determine the unit FCAS availabilities (section 7.1):

- RaiseReg Availability
  
  \[
  = \min \left[ 15, \frac{670 - 455}{1.1}, \text{ignore: lower slope coeff = 0, ignore: no Raise6Sec offered, ignore: no Raise60Sec offered, } (690 - 455 - (1 \times 50)), (465 - 455) \right]
  
  = \min \left[ 15, 193.5, \text{ignore, ignore, ignore, 185, 10} \right]
  
  = 10 \text{ MW}
  
- LowerReg Availability
  
  \[
  = \min \left[ 10, \text{ignore: upper slope coeff = 0, (455 - 300) / 1, ignore: no Lower6Sec offered, ignore: no Lower60Sec offered, } (455 - 290 - (1 \times 50)), (455 - 440) \right]
  
  = \min \left[ 10, \text{ignore, 155, ignore, ignore, 115, 15} \right]
  
  = 10 \text{ MW}
  
- Raise5Min Availability
  
  \[
  = \min \left[ 66, \frac{690 - 455}{1}, \frac{455 - 290}{0.15}, (690 - 455 - 10) / 1 \right]
  
  = \min \left[ 66, 235, 1089, 225 \right]
  
  = 66 \text{ MW}
  
- Lower5Min Availability
  
  \[
  = \min \left[ 76, \text{ignore: upper slope coeff = 0, } (455 - 290) / 1, (455 - 290 - 10) / 1 \right]
  
  = \min \left[ 76, \text{ignore, 165, 155} \right]
  
  = 76 \text{ MW}
MEASURES AND ABBREVIATIONS

Units of measure

<table>
<thead>
<tr>
<th>Abbreviation</th>
<th>Unit of measure</th>
</tr>
</thead>
<tbody>
<tr>
<td>$/MWh</td>
<td>Dollars per megawatt hour</td>
</tr>
<tr>
<td>MW</td>
<td>Megawatt</td>
</tr>
</tbody>
</table>

Abbreviations

<table>
<thead>
<tr>
<th>Abbreviation</th>
<th>Expanded name</th>
</tr>
</thead>
<tbody>
<tr>
<td>AEMO</td>
<td>Australia Energy Market Operator</td>
</tr>
<tr>
<td>AGC</td>
<td>Automatic Generation Control</td>
</tr>
<tr>
<td>FCAS</td>
<td>Frequency Control Ancillary Services</td>
</tr>
<tr>
<td>NEMDE</td>
<td>National Electricity Market Dispatch Engine</td>
</tr>
<tr>
<td>Rules</td>
<td>National Electricity Rules</td>
</tr>
<tr>
<td>SCADA</td>
<td>Supervisory Control and Data Acquisition</td>
</tr>
<tr>
<td>UIGF</td>
<td>Unconstrained Intermittent Generation Forecast</td>
</tr>
</tbody>
</table>